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Statistical aspects of determinantal point processes

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Introduction	Definition	Simulation	Parametric models	Inference



2 Definition, existence and basic properties

3 Simulation

4 Parametric models





Introduction	Definition	Simulation	Parametric models	Inference
Introduction	n			

- Determinantal point processes (DPP) form a class of repulsive point processes.
- They were introduced in their general form by O. Macchi in 1975 to model fermions (i.e. particules with repulsion) in quantum mechanics.
- Particular cases include the law of the eigenvalues of certain random matrices (Gaussian Unitary Ensemble, Ginibre Ensemble,...)
- Most theoretical studies have been published in the 2000's.
- The statistical aspects have so far been largely unexplored.

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Examples				



Poisson

DPP

DPP with stronger repulsion

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Statistical r	notivation			

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Statistical n	notivation			

 \longrightarrow Answer: **YES**.



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 \longrightarrow Answer: **YES**.

In fact:

- DPP's can be easily simulated.
- There are closed form expressions for the moments.
- There is a closed form expression for the density of a DPP on any bounded set.

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• Inference is feasible, including likelihood inference.

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- DPP's can be easily simulated.
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- Inference is feasible, including likelihood inference.

These properties are unusual for Gibbs point processes which are commonly used to model inhibition (e.g. the Strauss process).

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2 Definition, existence and basic properties

3 Simulation







Introduction	Definition	Simulation	Parametric models	Inference
Notation				

■ We view a spatial point process X on ℝ^d as a random locally finite subset of ℝ^d.

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• For any borel set $B \subseteq \mathbb{R}^d$, $X_B = X \cap B$.

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- We view a spatial point process X on ℝ^d as a random locally finite subset of ℝ^d.
- For any borel set $B \subseteq \mathbb{R}^d$, $X_B = X \cap B$.
- For any integer n > 0, denote ρ⁽ⁿ⁾ the n'th order product density function of X.
 Intuitively,

$$\rho^{(n)}(x_1,\ldots,x_n)\,\mathrm{d}x_1\cdots\mathrm{d}x_n$$

is the probability that for each i = 1, ..., n, X has a point in a region around x_i of volume dx_i .

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In particular $\rho = \rho^{(1)}$ is the *intensity function*.

For any function $C : \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{C}$, denote $[C](x_1, \ldots, x_n)$ the $n \times n$ matrix with entries $C(x_i, x_j)$.

Ex.:
$$[C](x_1) = C(x_1, x_1)$$
 $[C](x_1, x_2) = \begin{pmatrix} C(x_1, x_1) & C(x_1, x_2) \\ C(x_2, x_1) & C(x_2, x_2) \end{pmatrix}$

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Definition

X is a determinantal point process with kernel C, denoted $X \sim \text{DPP}(C)$, if its product density functions satisfy

$$\rho^{(n)}(x_1,\ldots,x_n) = \det[C](x_1,\ldots,x_n), \quad n = 1, 2, \ldots$$

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<u>For existence</u>, conditions on the kernel C are mandatory, e.g. C must satisfy: for all x_1, \ldots, x_n , det $[C](x_1, \ldots, x_n) \ge 0$.

Introduction	Definition	Simulation	Parametric models	Inference
First proper	rties			

 $\rho^{(n)}(x_1,\ldots,x_n) \approx 0 \quad \text{whenever} \quad x_i \approx x_j \quad \text{for some } i \neq j,$

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- The intensity of X is $\rho(x) = C(x, x)$.
- The pair correlation function is

$$g(x,y) := \frac{\rho^{(2)}(x,y)}{\rho(x)\rho(y)} = 1 - \frac{C(x,y)C(y,x)}{C(x,x)C(y,y)}$$

• Thus $g \leq 1$ (i.e. repulsiveness).

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- Any smooth transformation or independent thinning of a DPP is still a DPP with explicit given kernel.

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• There exists at most one DPP(C).

Introduction	Definition	Simulation	Parametric models	Inference
Existence				

In all that follows we assume

(C1) C is a continuous complex covariance function.

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In all that follows we assume

(C1) C is a continuous complex covariance function.

By Mercer's theorem, for any compact set $S \subset \mathbb{R}^d$, C restricted to $S \times S$, denoted C_S , has a spectral representation,

$$C_S(x,y) = \sum_{k=1}^{\infty} \lambda_k^S \phi_k^S(x) \overline{\phi_k^S(y)}, \quad (x,y) \in S \times S,$$

where $\lambda_k^S \ge 0$ and $\int_S \phi_k^S(x) \overline{\phi_l^S(x)} \, \mathrm{d}x = \mathbf{1}_{\{k=l\}}$.

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Theorem (Macchi, 1975; Hough et al., 2009; our paper) Under (C1), existence of DPP(C) is equivalent to that

 $\lambda_k^S \leq 1$ for all compact $S \subset \mathbb{R}^d$ and all k.

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Introduction	Definition	Simulation	Parametric models	Inference
Density	on a compact	set S		

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Let $X_S \sim \text{DPP}_S(C_S)$ with $S \subset \mathbb{R}^d$ compact. Recall that $C_S(x, y) = \sum_{k=1}^{\infty} \lambda_k^S \phi_k^S(x) \overline{\phi_k^S(y)}$.

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Theorem (Macchi, 1975)

Assuming $\lambda_k^S < 1$, for all k, then X_S is absolutely continuous with respect to the homogeneous Poisson process on S with unit intensity, and has density

$$f(\{x_1,\ldots,x_n\}) = \exp(|S| - D) \det[\tilde{C}](x_1,\ldots,x_n),$$

where $D = -\sum_{k=1}^{\infty} \log(1 - \lambda_k^S)$ and $\tilde{C} : S \times S \to \mathbb{C}$ is given by

$$\tilde{C}(x,y) = \sum_{k=1}^{\infty} \frac{\lambda_k^S}{1 - \lambda_k^S} \phi_k^S(x) \overline{\phi_k^S(y)}$$

Introduction	Definition	Simulation	Parametric models	Inference



2 Definition, existence and basic properties

3 Simulation







Let $X_S \sim \text{DPP}_S(C_S)$ where $S \subset \mathbb{R}^d$ is compact.

We want to simulate X_S .

Recall that $C_S(x,y) = \sum_{k=1}^{\infty} \lambda_k^S \phi_k^S(x) \overline{\phi_k^S(y)}.$



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We want to simulate X_S .

Recall that $C_S(x,y) = \sum_{k=1}^{\infty} \lambda_k^S \phi_k^S(x) \overline{\phi_k^S(y)}.$

Theorem (Hough et al., 2006)

For $k \in \mathbb{N}$, let B_k be independent Bernoulli r.v.'s with means λ_k^S . Define

$$K(x,y) = \sum_{k=1}^{\infty} B_k \phi_k^S(x) \overline{\phi_k^S(y)}, \quad (x,y) \in S \times S$$

Then $DPP_S(C_S) \stackrel{d}{=} DPP_S(K)$.

Introduction	Definition	Simulation	Parametric models	Inference

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Let $M = \max\{k \ge 0; B_k \ne 0\}$. Note that M is a.s. finite, since $\sum \lambda_k^S = \int_S C(x, x) \, \mathrm{d}x < \infty$.

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• simulate a realization M = m (by the inversion method);

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- **2** generate the Bernoulli variables B_1, \ldots, B_{m-1} (these are independent of $\{M = n\}$);

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- **(**) simulate a realization M = m (by the inversion method);
- **2** generate the Bernoulli variables B_1, \ldots, B_{m-1} (these are independent of $\{M = n\}$);
- (a) simulate the point process $DPP_S(K)$ given B_1, \ldots, B_M and M = m.

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So simulating X_S is equivalent to simulate $DPP_S(K)$ with

$$K(x,y) = \sum_{k=1}^{\infty} B_k \phi_k^S(x) \overline{\phi_k^S(y)}, \quad (x,y) \in S \times S$$

Let $M = \max\{k \ge 0; B_k \ne 0\}$. Note that M is a.s. finite, since $\sum \lambda_k^S = \int_S C(x, x) \, \mathrm{d}x < \infty$.

- **(**) simulate a realization M = m (by the inversion method);
- **2** generate the Bernoulli variables B_1, \ldots, B_{m-1} (these are independent of $\{M = n\}$);
- (a) simulate the point process $DPP_S(K)$ given B_1, \ldots, B_M and M = m.

In step 3, the kernel K becomes a *projection kernel*, and w.l.o.g.

$$K(x,y) = \sum_{k=1}^{n} \phi_k^S(x) \overline{\phi_k^S(y)}$$

where $n = \#\{1 \le k \le M : B_k = 1\}.$

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Denoting $\boldsymbol{v}(x) = (\phi_1^S(x), \dots, \phi_n^S(x))^T$, we have $K(x, y) = \sum_{k=1}^n \phi_k^S(x) \overline{\phi_k^S(y)} = \boldsymbol{v}(y)^* \boldsymbol{v}(x)$

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The point process $DPP_S(K)$ has a.s. *n* points (X_1, \ldots, X_n) that can be simulated by the following Gram-Schmidt procedure:

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sample X_n from the distribution with density $p_n(x) = ||\boldsymbol{v}(x)||^2/n$. set $\boldsymbol{e}_1 = \boldsymbol{v}(X_n)/||\boldsymbol{v}(X_n)||$. for i = (n-1) to 1 do sample X_i from the distribution (given X_{i+1}, \ldots, X_n) :

$$p_i(x) = \frac{1}{i} \left[\|\boldsymbol{v}(x)\|^2 - \sum_{j=1}^{n-i} |\boldsymbol{e}_j^* \boldsymbol{v}(x)|^2 \right], \quad x \in S$$

set $\boldsymbol{w}_i = \boldsymbol{v}(X_i) - \sum_{j=1}^{n-i} \left(\boldsymbol{e}_j^* \boldsymbol{v}(X_i) \right) \boldsymbol{e}_j, \ \boldsymbol{e}_{n-i+1} = \boldsymbol{w}_i / \|\boldsymbol{w}_i\|$

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Simulation of determinantal projection processes

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Theorem

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 $\{X_1, \ldots, X_n\}$ generated as above has distribution $DPP_S(K)$.

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Example: Let $S = [-1/2, 1/2]^2$ and

$$\phi_k(x) = e^{2\pi i k \cdot x}, \quad k \in \mathbb{Z}^2, \ x \in S,$$

for a set of indices k_1, \ldots, k_n in \mathbb{Z}^2 . So the projection kernel writes

$$K(x,y) = \sum_{j=1}^{n} e^{2\pi i k_j \cdot (x-y)}$$

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and $X_S \sim \text{DPP}_S(K)$ is homogeneous and has a.s. *n* points.

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Illustration	of simulation	on algorithm	n	

Step 1. The first point is sampled uniformly on S



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Step 3. The next point is sampled w.r.t. the following density :



Illustration of simulation algorithm

etc.



Illustration of simulation algorithm

etc.



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etc.



Illustration of simulation algorithm

etc.



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2 Definition, existence and basic properties

3 Simulation

4 Parametric models





Introduction	Definition	Simulation	Parametric models	Inference
Stationary :	models			

We focus on a kernel C of the form

$$C(x,y) = C_0(x-y), \quad x,y \in \mathbb{R}^d.$$

(C1) C_0 is a continuous covariance function Moreover, if $C_0 \in L^2(\mathbb{R}^d)$ we can define its Fourier transform

$$\varphi(x) = \int C_0(t) \mathrm{e}^{-2\pi \mathrm{i}x \cdot t} \,\mathrm{d}t, \quad x \in \mathbb{R}^d.$$

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Under (C1), if $C_0 \in L^2(\mathbb{R}^d)$, then existence of $DPP(C_0)$ is equivalent to

 $\varphi \leq 1.$

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Stationary a	models			

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$$\varphi \leq 1.$$

To construct parametric families of DPP : Consider parametric families of C_0 and rescale so that $\varphi \leq 1$. \rightarrow This will induce a bound on the parameter space. Several parametric families of covariance function are available, with closed form expressions for their Fourier transform.

• For d = 2, the circular covariance function with range α is given by

$$C_0(x) = \rho \frac{2}{\pi} \left(\arccos(\|x\|/\alpha) - \|x\|/\alpha \sqrt{1 - (\|x\|/\alpha)^2} \right) \mathbf{1}_{\|x\| < \alpha}.$$

 $\mathrm{DPP}(C_0) \text{ exists iff } \varphi \leq 1 \Leftrightarrow \rho \alpha^2 \leq 4/\pi.$

 \Rightarrow Tradeoff between the intensity ρ and the range of repulsion α .

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 $\Rightarrow \text{Tradeoff between the intensity } \rho \text{ and the range of repulsion } \alpha.$ Whittle-Matérn (includes Exponential and Gaussian) :

$$C_0(x) = \rho \frac{2^{1-\nu}}{\Gamma(\nu)} \|x/\alpha\|^{\nu} K_{\nu}(\|x/\alpha\|), \quad x \in \mathbb{R}^d$$

 $\operatorname{DPP}(C_0)$ exists iff $\rho \leq \frac{\Gamma(\nu)}{\Gamma(\nu+d/2)(2\sqrt{\pi}\alpha)^d}$.

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Generalized Cauchy

$$C_0(x) = \frac{\rho}{\left(1 + \|x/\alpha\|^2\right)^{\nu+d/2}}, \quad x \in \mathbb{R}^d.$$

DPP(C₀) exists iff $\rho \le \frac{\Gamma(\nu+d/2)}{\Gamma(\nu)(\sqrt{\pi\alpha})^d}.$

Introduction	Definition	Simulation	Parametric models	Inference

Pair correlation functions of $DPP(C_0)$ for previous models :

In blue : C_0 is the circular covariance function.

In red : C_0 is Whittle-Matérn, for different values of ν

In green : C_0 is generalized Cauchy, for different values of ν The parameter α is chosen such that the range of corr. ≈ 1 .



Introduction	Definition	Simulation	Parametric models	Inference
Spectral ap	proach			

- Specify a parametric class of integrable functions $\varphi_{\theta} : \mathbb{R}^d \to [0, 1]$ (spectral densities).
- This is all we need for having a well-defined DDP.
- Is convenient for simulation and for (approximate) density calculations as seen later.

Introduction	Definition	Simulation	Parametric models	Inference
Spectral ap	proach			

- Specify a parametric class of integrable functions $\varphi_{\theta} : \mathbb{R}^d \to [0, 1]$ (spectral densities).
- This is all we need for having a well-defined DDP.
- Is convenient for simulation and for (approximate) density calculations as seen later.
- Example: *power exponential spectral model*:

$$\varphi_{\rho,\nu,\alpha}(x) = \rho \frac{\Gamma(d/2+1)\nu\alpha^d}{d\pi^{d/2}\Gamma(d/\nu)} \exp\left(-\|\alpha x\|^{\nu}\right)$$

with

$$\rho > 0, \quad \nu > 0, \quad 0 < \alpha < \alpha_{\max}(\rho, \nu) := \left(\frac{2\pi^{d/2}\Gamma(d/\nu + 1)}{\rho\Gamma(d/2)}\right)^{1/d}$$

IntroductionDefinitionSimulationParametric modelsInferencePower exponential spectral model:(isotropic)spectraldensities and pair correlation functions



Approximation of stationary models

Consider a stationary kernel C_0 and $X \sim \text{DPP}(C_0)$.

• The simulation and the density of X_S requires the expansion

$$C_S(x,y) = C_0(y-x) = \sum_{k=1}^{\infty} \lambda_k^S \phi_k^S(x) \overline{\phi_k^S(y)}, \quad (x,y) \in S \times S,$$

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but in general λ_k^S and ϕ_k^S are not expressible on closed form.

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but in general λ_k^S and ϕ_k^S are not expressible on closed form. • Consider the unit box $S = [-\frac{1}{2}, \frac{1}{2}]^d$ and the Fourier expansion

$$C_0(y-x) = \sum_{k \in \mathbb{Z}^d} c_k e^{2\pi i k \cdot (y-x)}, \quad y-x \in S.$$

The Fourier coefficients are

$$c_k = \int_S C_0(u) \mathrm{e}^{-2\pi \mathrm{i}k \cdot u} \,\mathrm{d}u \approx \int_{\mathbb{R}^d} C_0(u) \mathrm{e}^{-2\pi \mathrm{i}k \cdot u} \,\mathrm{d}u = \varphi(k)$$

which is a good approximation if $C_0(u) \approx 0$ for $|u| > \frac{1}{2}$.

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which is a good approximation if $C_0(u) \approx 0$ for $|u| > \frac{1}{2}$.

• Example: For the circular covariance, this is true whenever $\rho > 5$.

The approximation of $DPP(C_0)$ on S is then $DPP_S(C_{app,0})$ with

$$C_{\text{app},0}(x-y) = \sum_{k \in \mathbb{Z}^d} \varphi(k) e^{2\pi i (x-y) \cdot k}, \quad x, y \in S,$$

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where φ is the Fourier transform of C_0 .

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where φ is the Fourier transform of C_0 .

This approximation allows us

- to simulate $DPP(C_0)$ on S;
- to compute the (approximated) density of $DPP(C_0)$ on S.

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Introduction	Definition	Simulation	Parametric models	Inference



2 Definition, existence and basic properties

3 Simulation







Consider a stationary and isotropic parametric DPP(C), i.e.

$$C(x,y) = C_0(x-y) = \rho R_\alpha(||x-y||),$$

with $R_{\alpha}(0) = 1$.

The first and second moments are easily deduced:

- The intensity is ρ .
- The pair correlation function is

$$g(x,y) = g_0(||x-y||) = 1 - R_\alpha^2(||x-y||).$$

Ripley's K-function is easily expressible in terms of R_{α} : if d = 2,

$$K_{\alpha}(r) := 2\pi \int_0^r tg_0(t) \, \mathrm{d}t = \pi r^2 - 2\pi \int_0^r t |R_{\alpha}(t)|^2 \, \mathrm{d}t.$$

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Inference				

Parameter estimation can be conducted as follows.

- Estimate ρ by #{obs. points}/area of obs. window.
- **2** Estimate α
 - either by **minimum contrast** estimator (MCE):

$$\hat{\alpha} = \operatorname{argmin}_{\alpha} \int_{0}^{r_{\max}} \left| \sqrt{\widehat{K}(r)} - \sqrt{K_{\alpha}(r)} \right|^{2} \mathrm{d}r$$

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• or by **maximum likelihood** estimator: given $\hat{\rho}$, the likelihood is deduced from the kernel approximation.





- Solid lines: theoretical pair correlation function
- $\circ\,$ Circles: pair correlation from the approximated kernel

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Samples from the Gaussian model on $[0, 1]^2$:



Samples from the exponential model on $[0, 1]^2$:



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Introduction	Definition	Simulation	Parametric models	Inference
Estimation	of α from 2	200 realisati	ons	



Gaussian model

Exponential model

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IntroductionDefinitionSimulationParametric modelsInferenceExample:134Norwegian pinetrees observed in a 56×38 m region



Møller and Waagpetersen (2004): a five parameter multiscale process is fitted using elaborate MCMC MLE methods.

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Here we fit a more parsimonious DPP models.
Introduction	Definition	Simulation	Parametric models	Inference
First,				
Whi	ttle-Matérn m	nodel;		
Cau	chy model;			

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• Gaussian model: the best fit, but plots of summary statistics indicate a lack of fit.

Introduction	Definition	Simulation	Parametric models	Inference
First,				
Whi	ttle-Matérn m	lodel;		
Cau	chy model;			
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 Gaussian model: the best fit, but plots of summary statistics indicate a lack of fit.

Second,

power exponential spectral model: provides a much better fit, with

$$\hat{\nu} = 10, \quad \hat{\alpha} = 6.36 \approx \alpha_{\max} = 6.77$$

i.e. close to the "most repulsive possible stationary DPP".

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Introduction	Definition	Simulation	Parametric models	Inference
Conclusions				

• DPP's provide flexible parametric models of repulsive point processes.

Introduction	Definition	Simulation	Parametric models	Inference
Conclusions				

- DPP's provide flexible parametric models of repulsive point processes.
- DPP's possess the following appealing properties:
 - Easily simulated.
 - Closed form expressions for the moments.
 - Closed form expression for the density of a DPP on any bounded set.

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• Inference is feasible, including likelihood inference.

Introduction	Definition	Simulation	Parametric models	Inference
Conclusions				

- DPP's provide flexible parametric models of repulsive point processes.
- DPP's possess the following appealing properties:
 - Easily simulated.
 - Closed form expressions for the moments.
 - Closed form expression for the density of a DPP on any bounded set.
 - Inference is feasible, including likelihood inference.
- \Rightarrow Promising alternative to repulsive Gibbs point processes.

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