

A Stochastic Space-time Model for Intermittent Precipitation Occurrences

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Stochastic Weather Generators

- ▶ Stochastic weather generators:
 - ▶ Provide fast and realistic simulations of atmospheric variables.
 - ▶ Facilitate understanding the probabilistic structure.
 - ▶ Required by impact studies.
- ▶ Note:
 - ▶ Statistical models, not forecast models.
 - ▶ Reproduce reality accurately in a distributional sense.
 - ▶ Different from climate numerical models.
- ▶ Precipitation has been a key variable of interest.
 - ▶ Serves as input into hydrologic and agricultural models.



Features of Precipitation Field

- ▶ Intermittent nature and high variability.
- ▶ Spatio-temporal dependence.
- ▶ Precipitation statistics are strongly scale dependent.
 - ▶ Data are measured as averages over space-time scales.
- ▶ Rainfall zeros: precipitation occurrences.
 - ▶ Especially for small time scales.
 - ▶ Contribute significantly to the observed dependence.
 - ▶ An important component in stochastic weather simulations.
- ▶ Intensity: non-Gaussian.

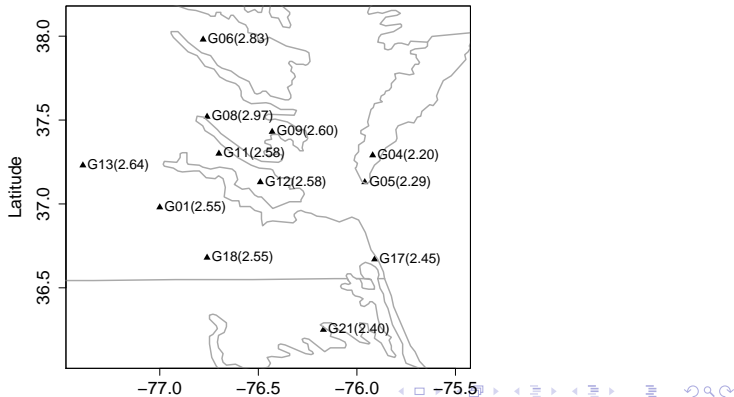


Our Contributions

- ▶ Consistent model for precipitation occurrences:
 - ▶ Shorter time scale: 15-minute rain gauge data.
 - ▶ Generate realistic spatio-temporal dependence.
- ▶ Model framework:
 - ▶ Truncated spatio-temporal non-Gaussian random field model.
- ▶ Model diagnostics:
 - ▶ Define meaningful precipitation statistics.
 - ▶ Develop visualization methods for the assessment of spatio-temporal dependence.
- ▶ Model assessment is important.
 - ▶ Reproducing means of the precipitation.
 - ▶ Reproducing “higher moments”: dependence.



Gauge Locations



Rain Gauge Data

- ▶ High-frequency gauge-based space-time data:
 - ▶ Time records of each bucket tip (0.01 inches) at each location.
 - ▶ 12 Gauges from 05/19/2004 to 05/17/2007.
 - ▶ Aggregate to different time scales.
 - ▶ Unit: mm/hr.
- ▶ Percentage of rain for different time scales:

Time	10-min	15-min	30-min	1-hr	3-hr
Occurrence	1.77	2.55	4.91	6.47	10.42
Time	6-hr	1-day	1-week	1-mon	3-mon
Occurrence	14.77	32.72	88.57	99.76	100



Truncated Model

- ▶ Bell (1987): the truncated Gaussian random field model

$$W(\mathbf{x}) = \begin{cases} f(Z(\mathbf{x})), & Z(\mathbf{x}) > c; \\ 0, & Z(\mathbf{x}) \leq c. \end{cases}$$

- ▶ Stein (1992) considered Monte Carlo methods for prediction and inference for truncated spatial data based on this model.
- ▶ For 15-minute rain rates:
 - ▶ The value of c is high.
 - ▶ GRF has thin tail distributions.
 - ▶ The probability of exceeding c at many locations is low.
 - ▶ It may not be sufficient to describe the dependence in the occurrence.



- ▶ t random field model (Røislien and Omre, 2006) is specified by
 - ▶ Mean function: $\mu(\mathbf{x})$.
 - ▶ Positive definite scale function: $\kappa(\mathbf{x}, \mathbf{x}')$.
 - ▶ The degrees of freedom: ν .
- ▶ The tRF tends towards a GRF as $\nu \rightarrow \infty$.



Representation of Spatial tRF Model

- ▶ Univariate t random variable has the representation

$$T = \frac{Z}{\sqrt{V/\nu}}.$$

- ▶ T has a heavier tail due to the random scaling $\sqrt{V/\nu}$.
- ▶ Similarly, the multivariate t random vector for n locations

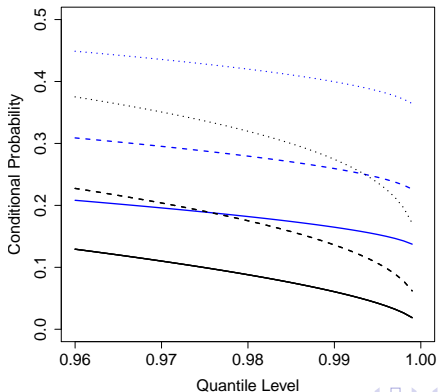
$$\mathbf{Y} = \boldsymbol{\mu} + \frac{\mathbf{Z}}{U}, \quad \nu U^2 \sim \chi^2(\nu).$$

- ▶ Given $U = u$, $\mathbf{Y} \sim N_n(\boldsymbol{\mu}, \boldsymbol{\Omega}/u)$.
- ▶ The variability across realizations of \mathbf{Y} is larger.
- ▶ A higher probability that \mathbf{Y} exceeds c at many locations.
- ▶ tRF tends towards GRF as $\nu \rightarrow \infty$.



Bivariate Illustration

$P(Y_2 > c | Y_1 > c)$: $\nu = 3, \infty$ and $\rho = 0.3, 0.5, 0.7$.



- ▶ Define the dry and the rain event:

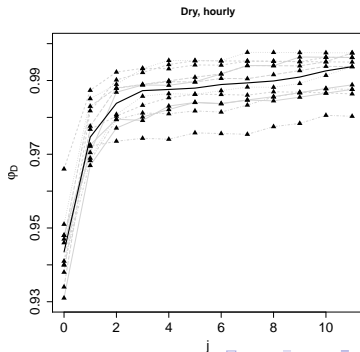
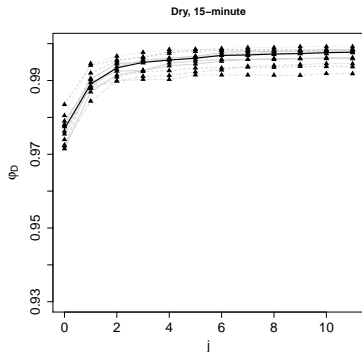
$$D(\mathbf{x}) = \{Y(\mathbf{x}) \leq c\}, \quad R(\mathbf{x}) = \{Y(\mathbf{x}) > c\}.$$

- ▶ Precipitation statistics:

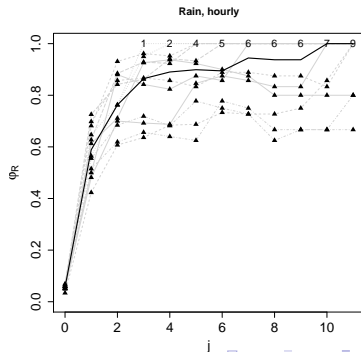
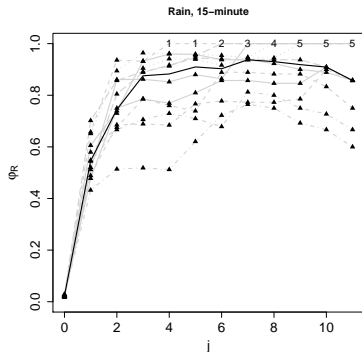
- ▶ Marginal dry: $p_D = Pr(D(\mathbf{x}))$.
- ▶ Marginal rain: $p_R = Pr(R(\mathbf{x})) = 1 - p_D$.
- ▶ Conditional dry: $p_{D|D} = Pr(D(\mathbf{x})|D(\mathbf{x}'))$.
- ▶ Conditional rain: $p_{R|R} = Pr(R(\mathbf{x})|R(\mathbf{x}'))$.



Conditional Dry Probability Plot

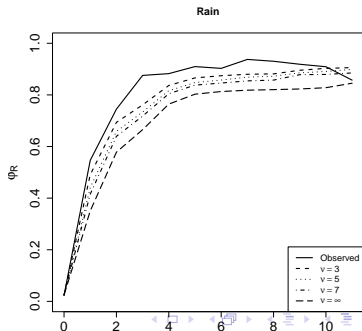
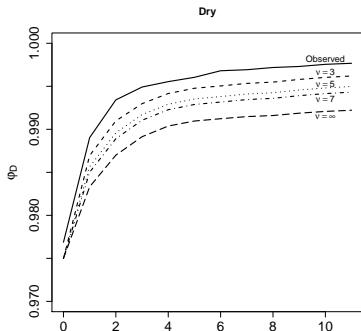


Conditional Rain Probability Plot



Comparing Model Simulations

- ▶ Purely spatial truncated tRF models with zero-mean.
- ▶ Degrees of freedom: $\nu = 3, 5, 7, \infty$.
- ▶ The marginal dry probability: 97.5%.



Space-time tRF Model

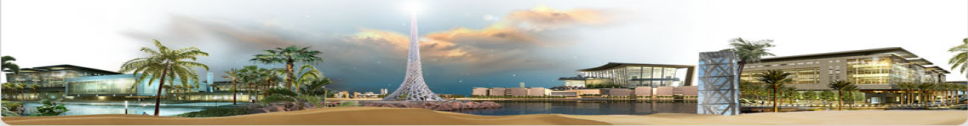
- ▶ We propose a more flexible space-time tRF model

$$Y(\mathbf{x}, t) = \frac{Z(\mathbf{x}, t)}{U(t)},$$

- ▶ $Z(\mathbf{x}, t)$: a zero-mean stationary GP with ACF $K(\mathbf{x}, t)$.
- ▶ $\nu U^2(t)$: a stationary Gamma process, where

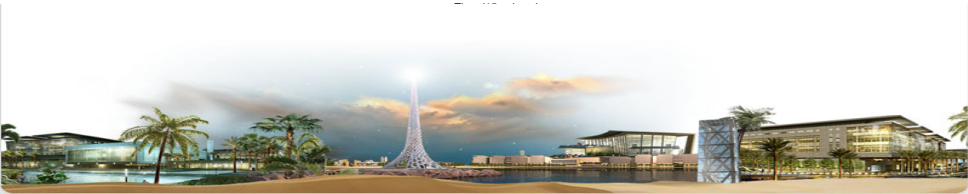
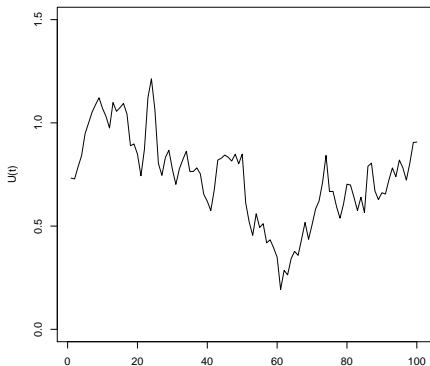
$$U^2(t) = \frac{1}{\nu} \sum_{j=1}^{\nu} X_j^2(t),$$

- ▶ $X_j(t)$'s are i.i.d. zero-mean stationary Gaussian processes.
- ▶ For any given time $t = t^*$,
 - ▶ $\nu U^2(t^*)$ is χ_{ν}^2 distributed.
 - ▶ It follows that $Y(\mathbf{x}, t^*)$ is a spatial tRF.



Simulated $U(t)$ Process

Temporal range parameter $\alpha_U = 0.5$, $\nu = 3$.



Spatio-temporal Covariance Function

- ▶ Stein (2005): spectral-in-time representation of K for data taken regularly in time at a modest number of sites,

$$K(\mathbf{x}, t) = \int_{\mathbb{R}} S(\omega) C(|\mathbf{x}| \gamma(\omega)) e^{i\mathbf{u}'\mathbf{x}\theta(\omega) + i\omega t} d\omega.$$

- ▶ All the functions have natural interpretations.
- ▶ Parameterization for even positive functions:

$$\log\{\gamma(\omega)\} = \sum_{k=0}^L a_k \cos(k\omega),$$

$$\log\{S(\omega)\} = -\beta \log\left(\sin\left|\frac{1}{2}\omega\right|\right) + \sum_{k=0}^L c_k \cos(k\omega).$$



- ▶ Parameters of interest are:
 - ▶ α : the spatial range in C (Matérn).
 - ▶ β : measures the long-range time dependence in S .
 - ▶ α_U : dependence range in the $U(t)$ process.
 - ▶ ν : degrees of freedom.



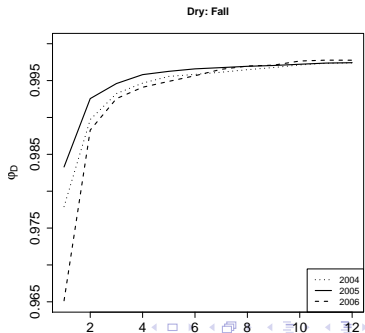
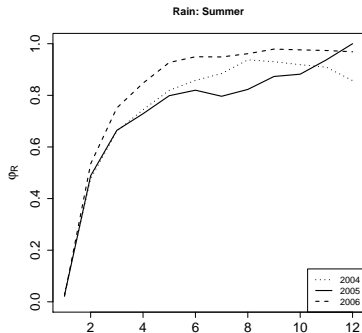
Application to Rain Gauge Data

- ▶ Conditional probability plots for four seasons from Summer 2004 to Spring 2007.
- ▶ Look for patterns of the precipitation occurrences:
 - ▶ Precipitation over a larger region and/or last longer time.
 - ▶ Local storms.



El Niño Years?

- ▶ The years 2004 and 2006: weak El Niño years.
- ▶ The study region is not typically affected by the El Niño effect in terms of total precipitation; How about spatial patterns?



Model Fitting

- ▶ Empirical approach: based on Monte Carlo simulations.
 - ▶ Minimizing the difference of the conditional probabilities obtained from the model and from the observations.
- ▶ The estimates of $(\alpha, \beta, \alpha_u, \nu)$ for Summer 2004-2006.

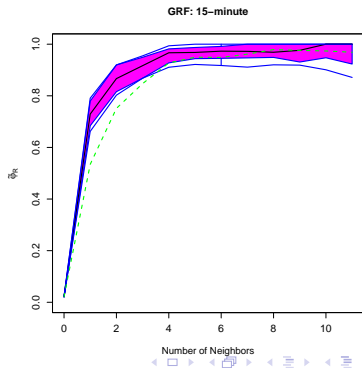
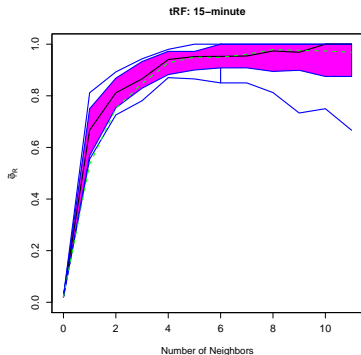
Year	$\hat{\alpha}$	$\hat{\beta}$	$\hat{\alpha}_u$	$\hat{\nu}$
2004	0.485	0.486	0.199	4
2005	0.495	0.558	0.232	5
2006	0.500	0.652	0.175	3

- ▶ Summer 2006:
 - ▶ $(\hat{\alpha}, \hat{\beta}) = (0.811, 0.123)$ for the truncated GRF model.
 - ▶ The estimate of the spatial range parameter is much larger.



Model Diagnostics: Summer 2006

- ▶ Compare the conditional rain probabilities by the functional boxplot (Sun and Genton, 2011).



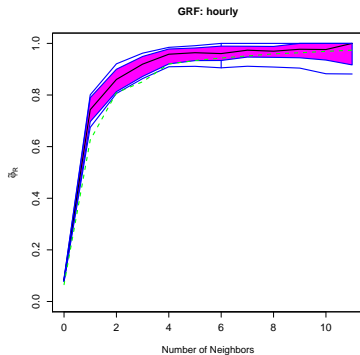
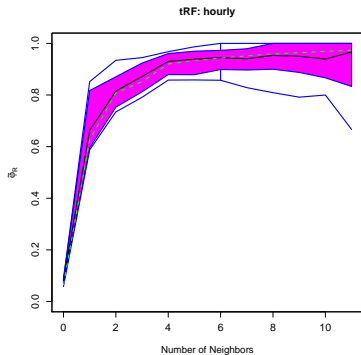
Consistent Spatio-temporal Model

- ▶ Another important aspect: wet or dry spell.
- ▶ Temporal dependence is necessary to produce them correctly.
- ▶ From a statistical modeling point of view
 - ▶ It is desirable to have a consistent space-time model to produce precipitation features at different scales.
 - ▶ Rather than to have a separate model for each scale.
- ▶ In order to produce the desired rain or dry spells at larger scales through aggregation
 - ▶ Need to characterize the complex dependence structure precisely at small space-time scales.
- ▶ We can use aggregation to assess model performance.



Model Diagnostics: Summer 2006

- ▶ Aggregate to hourly data



- ▶ Estimation:
 - ▶ Generate data at 12 locations and 8736 time points.
 - ▶ Circulant embedding techniques.
 - ▶ FFT for fast and exact simulations (Wood and Chan, 1994; Helgason et al., 2011).
- ▶ Simulation on a grid.



- ▶ A stochastic space-time model for precipitation occurrence:
 - ▶ Truncated tRF model with random scaling $U(t)$.
 - ▶ The increased variability is useful for shorter time scale.
- ▶ Model assessment:
 - ▶ Conditional probability plot, and aggregation.
 - ▶ Functional boxplot: the fast algorithm (Sun et al., 2012).
- ▶ Precipitation intensity:
 - ▶ More complete analysis: includes the positive rainfall amounts.
 - ▶ Investigate Bayesian inference methods.

