Stochastic rainfall seasonality: Estimation and applications

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Stochastic seasonality

Seasons are not consistently deterministic.

- Stochastic seasonal variation accommodates more intra-annual variability
- A stochastic model for seasonality can be used to describe observed seasonal variability
- Conditional seasonality can be used to improve prediction



Within season rainfall model

Based on Wilks (1998) and Thompson *et al.* (2007) This is a (partially) hidden three state model:

$$\circ \; S_t(k) = 0 \;\;$$
 dry

$$\circ \,\, S_t(k) = 1 \,\,\,$$
 light rain

$$\circ \,\, S_t(k) = 2 \,\,$$
 heavy rain

The rainfall for each site k and time t is

$$R_t(k) = eta_{S_t(k)}(k) X_t(k)$$

where the $X_t(k)$ are temporally independent unit exponentials.

Six (dynamic) parameters per site:

$$egin{aligned} p_i(k) &= P(S_t(k) = 0 | S_{t-1}(k) = i) \ lpha_i(k) &= P(S_t(k) = 1 | S_t(k)
eq 0, S_{t-1}(k) = i) \ (i = 0, 1, 2) \end{aligned}$$



Spatial dependence is built into $R_t(k)$ through:

$$X_t(k) = -\log(oldsymbol{\Phi}(V_t(k)))$$

and $S_t(k)$ using:

$$S_t(k) = egin{cases} 0 & U_t(k) \leq a_i(k) \ 1 & a_i(k) < U_t(k) \leq b_i(k) \ 2 & U_t(k) > b_i(k) \end{cases}$$

where

$$egin{aligned} a_i(k) &= oldsymbol{\Phi}^{-1}(p_i(k)) \ b_i(k) &= oldsymbol{\Phi}^{-1}(p_i(k) + lpha_i(k)(1-p_i(k))) \end{aligned}$$

 \mathbf{U}_t and \mathbf{V}_t are Gaussian processes based on separate correlation matrices, $\mathbf{\Omega}$ and $\mathbf{\Psi}$

Season switching model

• Variable season onset dates

○ Variable season lengths

- Seasons strictly sequential
- Cyclical seasons
- Seasons common to all sites in region

Daily rainfall is dynamically classified into homogeneous seasonal regimes with stochastic onsets and durations. Traditionally defined seasons are replaced with "season change intervals" defined by "season anchor points".



Shading denotes season change intervals; colours denote seasons; filled circles denote season anchor points.

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Within any season change interval there are only **two possible seasons**.

The season change indictor

$$C_t = egin{cases} 0 & ext{mover state} \ 1 & ext{stayer} \end{cases}$$

is a Markov chain with transition probability matrix

$$\mathbf{Q}(d)= egin{bmatrix} 1-q(d) & q(d)\ 0 & 1 \end{bmatrix}$$

Boundary conditions are also necessary to ensure $C_t = 0$ at the start and $C_t = 1$ at the end of the season change interval.

Examples of q(d)

This can be any discrete function. For example the hazard function, q(d), can come from:

- a step function
- a Beta distribution
- a uniform onset distribution

The uniform onset function is useful for investigating seasonality within the data, but it is not useful for prediction.

Parameters of q(d) can be estimated by maximising:

$$M = \sum_{t=2}^T \sum_{u=0}^1 \sum_{v=0}^1 \log \mathbf{Q}_{uv}(d_t) \gamma^{(uv)}(t)$$

where

$$\gamma^{(uv)}(t) = P_0(C_{t-1} = u, C_t = v | \mathbf{R}).$$

This can be evaluated, but the cost is prohibitive if the number if sites is not small.

A simple predictor of $\gamma^{(uv)}(t)$ is

$$ilde{\gamma}^{(uv)}(t) = rac{1}{K}\sum_{k=1}^K P(C_{t-1}=u,C_t=v|\mathbf{R}(k)).$$



These methods of estimating q(d), i.e.

○ mean over univariate estimates

• **median** over univariate estimates

both depend on combining the **daily probabilities** over space and time.

Another option is to use a

o classification rule

to choose the actual season change day for each site and season, then use the distribution of these days to characterise q(d).



Another option, is to estimate the multi-site $\gamma^{(uv)}(t)$ by combining multiple **bivariate** or **trivariate** estimates.

• mean over univariate estimates

• median over univariate estimates

classification rule

• combined **bivariate** or **trivariate** estimates

Different estimates can be compared to truth using simulated rainfall with known distribution of season onset dates.

By limiting the region to **5 sites**, $\gamma^{(uv)}(t)$ can be computed directly for comparison as well.







Climate drivers — El Niño

q(d) can be categorised into regimes by conditioning on a climate index such as the SOI.









Summary

The stochastic seasonal model can be used as an investigative tool to:

 move beyond rigid or sinusoidal seasons
 tease out weak seasonality and easily characterise strong seasonality

Conditioning seasonality on climate indices could improve the predictibility of the rainfall model.

 Stochastic rainfall generation could be driven from short range seasonal outlooks

 An additional mechanism to improve climate model downscaling